DIYPowerPCB

Introduction

Theoretical derivations in a lecture are part of everyday university life. But you can only really get to grips with topics if you apply what you have learned! For this reason, we have developed the DIY Power PCB. This enables us to provide all interested students with their own hardware platform to carry out a wide variety of experiments on the subject of power electronics.
The idea was not to build the most powerful or the smallest hardware, but a hardware whose components can largely be assembled automatically and which is above all inexpensive and robust. So no worries if a short circuit is generated or smoke rises 😉
The DIY Power PCB is used in various experiments in the lectures on power electronics and electrical drives and costs less than 20€ for our students when fully assembled.

Parameters:

- 3x half bridges
- Adjustable overcurrent shutdown
- ESP32 Wroom microcontroller
- 1.36 OLED display
- Max. 36V @10A input
- Hall sensor or encoder inputs
- General purpose analog input

- Reverse polarity protection

The brain of the board is represented by an ESP32 microcontroller. This controller is very powerful and widely available at affordable prices. You can directly program it using the Arduino IDE or ESP-IDF. For lab lessons, you will use a serial communication interface between MATLAB Simulink and the controller to command the board.

Schematic:

schematic_diy_power_pcb.pdf

To use the DIY Power PCB, you can program the ESP32 using the Arduino IDE or the ESPRESSIFWorkspace (Espressif-IDE) development platform. Arduino IDE is more intuitive; however, it is not capable of utilizing the full range of the timer units. Espressif-IDE allows you to access the full functionality of the microcontroller, and the programmer is also faster than the Arduino IDE. However, it is more complicated to get started with.
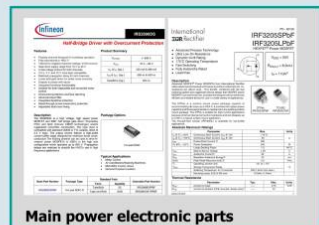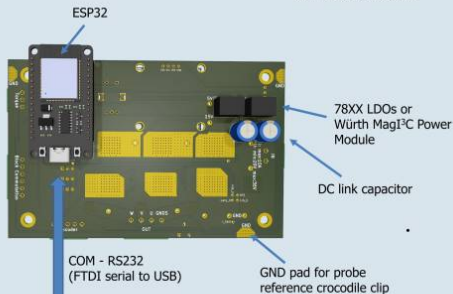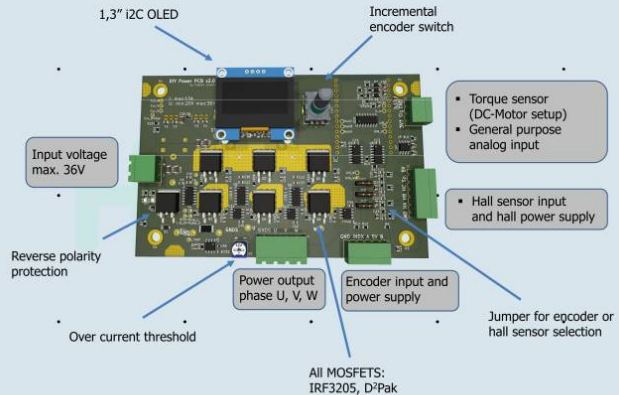
Board Flyer

DIY POWER PCB
Multi Purpose Power Electronic Board

Hochschule Konstanz
Fakultät Elektrotechnik
und Informationstechnik

HTWG EI

The DIY Power PCB can be used to build a wide variety of basic power electronics circuits. A simple buck converter can be set up with each of the three phases opposite the GNDS potential. If two phases are used, an inverter can be built with synchronous clocking or as a phase shifted full bridge. All three half bridges U, V, W can be used to control a BLDC motor and a synchronous machine or to generate a three-phase AC voltage in general.

1,3" i2C OLED

Incremental encoder switch

- Torque sensor (DC-Motor setup)
- General purpose analog input

Input voltage max. 36V

- Hall sensor input and hall power supply

Reverse polarity protection

Power output phase U, V, W

Encoder input and power supply

Jumper for encoder or hall sensor selection

Over current threshold

All MOSFETS:
IRF3205, D²Pak

ESP32

78XX LDOs or Würth MagI³C Power Module

DC link capacitor

COM - RS232 (FTDI serial to USB)

GND pad for probe reference crocodile clip

International Rectifier

IRF3205SPbF
IRF3205LPbF

Main power electronic parts

MATLAB

To use the DIY Power PCB, you can program the ESP32 using the Arduino IDE or the ESPRESSIFWorkspace (Espressif-IDE) development platform.
Arduino IDE is more intuitive, however, it is not capable of utilizing the full range of the timer units. Espressif-IDE allows you to access the full functionality of the microcontroller, the programmer is also faster than the Arduino IDE. However, it is more complicated to get started with.

Control options

Additional features:
- Maximum input current of 10A
- Optional ACS712_XX current sensors for every half bridge
- Adjustable over current threshold
- ESP32 with WiFi and Bluetooth connection

MinebeaMitsumi BLDC Motor

Dunkermotoren Brushed DC Motor GR 63x55

Faszination EI

Accessories

Würth Electronic Inductor / Capacitor

Prof. Dr.-Ing. Heinz Rebholz – HTWG Konstanz – heinz.rebholz@htwg-konstanz.de

Downloads

Version 2.2

Version 2.2 of DIY Power PCB KiCAD Files:

Download

If you want to generate fancy 3D images you have to download the model files:

Download 3D Models

The content of the .zip must be saved in the "3dmodels" folder of KiCAD in a new folder with the name "htwg.3dshapes".

If your PC does not recognize a USB-to-serial connection, you might not have installed the correct driver yet: Download the latest drivers: Link to FTDI

Known Bugs

Following Bugs will be removed within V3 soon:

- Flashing only works if the incremental encoder is in the correct position, as it blocks the UART signal at every second rotation stage.
- The incremental encoder only works if the ESP32 is also supplied via USB.
- As the internal resistance of the driver is considerably high (200 Ohm), the bootstrap capacitor is only recharged slowly. This means that only duty cycle values of up to approx. 90% are possible. In V3 the problem is solved by an additional external bootstrap diode.

Isolation

In many of our experiments, we control the hardware via the serial interface. To protect the connected PC, you should use galvanic isolation between the PC and the microcontroller board when the supply voltage is active. This prevents overvoltages from destroying the USB port even in the event of major errors in

the setup (short circuit or load dump) on the control PC.
The isolators are available in the laboratory.

z.B.